



HEIDENHAIN



**Functional
Safety**

Product Information

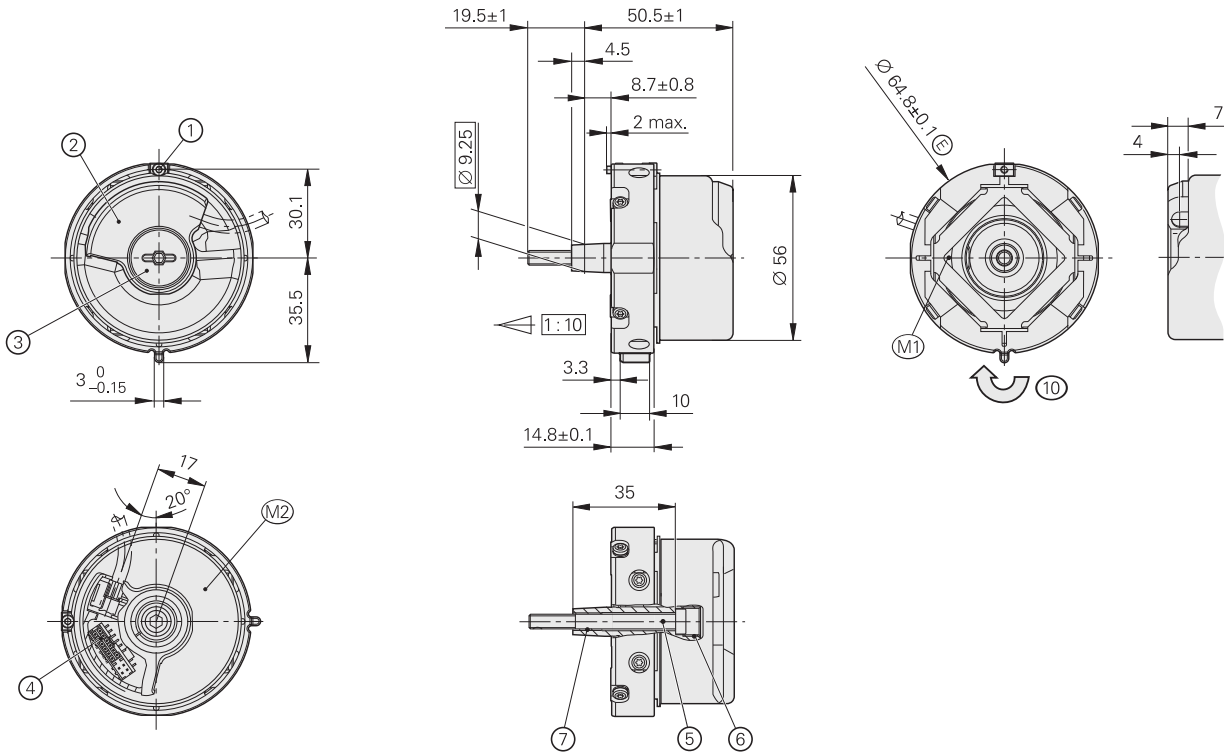
ECN 1325 EQN 1337

Absolute Rotary Encoders with
Taper Shaft for Safety-Related
Applications

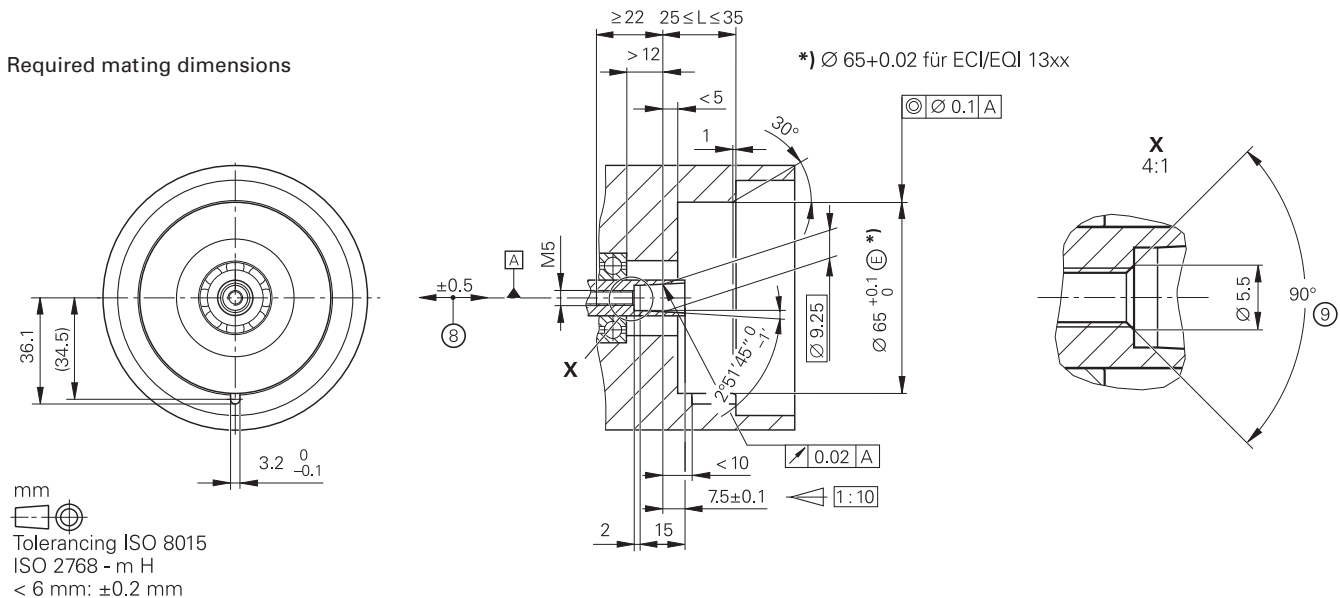
ECN 1325, EQN 1337

Rotary encoders for absolute position values with safe singleturn information

- Installation diameter 65 mm
- Expanding ring coupling 07B
- Taper shaft 65B



Required mating dimensions



- ▣ = Bearing of mating shaft
- M1= Measuring point for operating temperature
- M2= Measuring point for vibration, see D 741714
- 1 = Clamping screw for coupling ring, width A/F 2, tightening torque 1.25–0.2 Nm
- 2 = Die-cast cover
- 3 = Screw plug, widths A/F 3 and 4, tightening torque 5+0.5 Nm
- 4 = PCB connector, 12-pin and 4-pin
- 5 = Screw DIN 6912 – M5x50 – 08.8 – MKL width A/F 4, tightening torque 5+0.5 Nm
- 6 = Back-off thread M10
- 7 = Back-off thread M6
- 8 = Compensation of mounting tolerances and thermal expansion, no dynamic motion permitted
- 9 = Chamfer is obligatory at start of thread for materially bonding anti-rotation lock
- 10 = Direction of shaft rotation for output signals as per the interface description

Specifications	ECN 1325 – Singletum	EQN 1337 – Multitum
These data apply for	ID 678919-03/-53 ¹⁾	ID 678921-03/-53 ¹⁾
Functional safety For applications up to	<p>As single-encoder system for monitoring functions</p> <ul style="list-style-type: none"> SIL 1 according to EN 61508 (further basis for testing: EN 61800-5-2) Category 2 PL e according to EN ISO 13849-1:2008 <p>As single-encoder system for closed loop functions</p> <ul style="list-style-type: none"> SIL 2 according to EN 61508 (further basis for testing: EN 61800-5-2) Category 3, PL d according to EN ISO 13849-1:2008 <p>Safe in the singletum range</p>	
PFH	$\leq 10 \times 10^{-9}$ (probability of a dangerous failure per hour)	
Safe position ²⁾	<p>Encoder: $\pm 1.76^\circ$ (safety-related measuring step: SM = 0.7°)</p> <p>Mechanical coupling: $\pm 2^\circ$ (fault exclusion for loosening of shaft and stator coupling, designed for accelerations of $\leq 300 \text{ m/s}^2$)</p>	
Interface	EnDat 2.2	
Ordering designation	EnDat22	
Position values/revolution	33 554 432 (25 bits)	
Revolutions	-	4096 (12 bits)
Calculation time t_{cal} Clock frequency	$\leq 7 \mu\text{s}$ $\leq 8 \text{ MHz}$	
System accuracy	$\pm 20''$	
Electrical connection	PCB connector for rotary encoder: 12-pin; temperature sensor: ³⁾ 4-pin	
Cable length	$\leq 100 \text{ m}$ (see EnDat description in the catalog <i>Interfaces of HEIDENHAIN Encoders</i>)	
Voltage supply	3.6 V to 14 V DC	
Power consumption ⁴⁾ (maximum)	At 3.6 V: $\leq 600 \text{ mW}$ At 14 V: $\leq 700 \text{ mW}$	At 3.6 V: $\leq 700 \text{ mW}$ At 14 V: $\leq 800 \text{ mW}$
Current consumption (typical)	At 5 V: 85 mA (without load)	At 5 V: 105 mA (without load)
Shaft	Taper shaft $\varnothing 9.25 \text{ mm}$; taper 1:10 (65B)	
Spindle speed	$\leq 15\,000 \text{ min}^{-1}$	$\leq 12\,000 \text{ min}^{-1}$
Starting torque at 20° C	$\leq 0.01 \text{ Nm}$	
Moment of inertia of rotor	$2.6 \times 10^{-6} \text{ kgm}^2$	
Angular acceleration of rotor	$\leq 1 \times 10^5 \text{ rad/s}^2$	
Natural frequency of stator coupling	$\geq 1700 \text{ Hz}$	
Axial motion of measured shaft	$\leq \pm 0.5 \text{ mm}$	
Vibration 55 Hz to 2000 Hz Shock 6 ms	$\leq 300 \text{ m/s}^2$ (EN 60 068-2-6); 10 Hz to 55 Hz constant over distance 4.9 mm peak to peak $\leq 2000 \text{ m/s}^2$ (EN 60 068-2-27)	
Operating temperature	-40 °C to 115 °C	
Threshold sensitivity Error message for exceeded temperature	125 °C (measuring accuracy of internal temperature sensor: $\pm 7 \text{ K}$)	
Relative humidity	$\leq 93 \%$ (40 °C/21 d as per EN 60 068-2-78); without condensation	
Protection EN 60 529	IP 40 (see <i>Insulation</i> under <i>General mechanical information</i> in the <i>Encoders for Servo Drives</i> catalog; contamination through ingress of liquids must be avoided)	
Weight	$\approx 0.25 \text{ kg}$	

1) Mounting frame in collective package

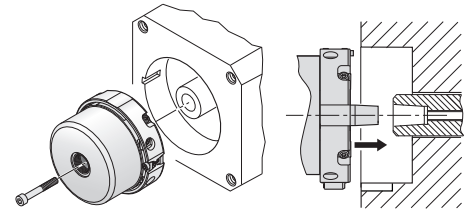
2) Further tolerances may occur in subsequent electronics after position value comparison (contact manufacturer of sub. electronics)

3) See *Temperature measurement in motors* in the *Position Encoders for Servo Drives* brochure

4) See *General electrical information* in the catalog *Interfaces for HEIDENHAIN Encoders*

Assembly

The taper shaft of the rotary encoder is slid onto the motor's drive shaft and fastened with a central screw. It is particularly important to ensure that the positive-locking element of the stator coupling securely engages the corresponding slot in the mating part. A screw with materially bonding anti-rotation lock is to be used (see *Mounting accessories*). The stator coupling is clamped by an axially tightened screw in a location bore.



Conditions required on the motor side for a safe mechanical connection:

	Mating shaft	Mating stator
Material	Steel	Aluminum
Tensile strength R_m	$\geq 600 \text{ N/mm}^2$	$\geq 220 \text{ N/mm}^2$
Interface pressure P_G	$\geq 500 \text{ N/mm}^2$	$\geq 200 \text{ N/mm}^2$
Surface roughness R_z	$\leq 10 \mu\text{m}$	$\leq 10 \mu\text{m}$
Coefficient of expansion α_{therm}	$(10 \text{ to } 17) \times 10^{-6} \text{ K}^{-1}$	$\leq 25 \times 10^{-6} \text{ K}^{-1}$

The following maximum torque M_{max} is to be used when designing the mechanical fault exclusion for the shaft connection:

$$M_{\text{max}} = J \times \alpha + 0.2 \text{ Nm}$$

where

J: Rotor moment of inertia (see Specifications of the encoder)

α : Rotor angular acceleration (see Specifications of the encoder)

The customer's mechanical design must ensure that the torque M_{actl} actually occurring in the application can be transmitted. This M_{actl} can be smaller than the M_{max} to be considered for designing the fault exclusion.

Mounting accessories

Screws

Screws (mounting screws, central screws) are not included in delivery. They can be ordered separately. The screws from HEIDENHAIN feature a coating as per DIN 267-27 which, after hardening, provides a materially bonding anti-rotation lock. For this reason the screws cannot be reused. Unused screws are not storable indefinitely. The minimum shelf life is 2 years (storage at $\leq 30 \text{ }^\circ\text{C}$ and $\leq 65 \%$ relative humidity). The expiration date is on the package.

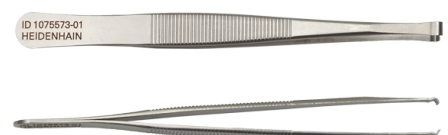
ECN 1325, EQN 1337	Screws ¹⁾	Lot size
Central screw for fastening the shaft	DIN 6912-M5×50-08.8-MKL	ID 202264-54
		10 or 100 pieces

1) With coating for materially bonding anti-rotation lock

Please note: The adhesive on the screws with materially bonding coating hardens quickly. Screw insertion and application of tightening torque must therefore take no longer than 5 minutes (see dimension drawing). The required strength is attained after 6 hours at room temperature. The curing time increases with decreasing temperature. Curing temperatures below $5 \text{ }^\circ\text{C}$ are not permissible.

Mounting aid for engaging and disengaging the PCB connector. The mounting aid prevents damage to the cable because it applies the pulling force solely to the connector. Tension must not be applied to the wires.

ID 1075573-01



For further mounting information and mounting aids see the Mounting Instructions and the catalog *Encoders for Servo Drives*

Integrated temperature evaluation

This rotary encoder features a temperature sensor integrated in the encoder electronics and an evaluation circuit for an external temperature sensor. In both cases, the respective digitized temperature value is transmitted purely serially over the EnDat protocol. It must be noted in both cases that temperature measurement and transmission is not "safe" in the sense of functional safety.



With regard to the internal temperature sensor, the rotary encoder supports a dual-level cascaded signaling of exceeded temperature. It consists of an EnDat warning and an EnDat error message.

In accordance with the EnDat specification, when the warning threshold of the internal temperature sensor is reached, an EnDat warning is transmitted (EnDat operating condition memory area, word 1 – "warnings," bit 2¹ – "temperature exceeded"). This warning threshold for the internal temperature sensor is saved in the EnDat operational-parameter memory area, word 6 – "Threshold sensitivity warning bit for exceeded temperature," and can be individually adjusted. A device-specific default value is saved here when the encoder is shipped. The temperature measured by the internal temperature sensor is higher by a device-specific and application-specific amount than the temperature at the measuring point M1 according to the dimension drawing.





The rotary encoder features a further, but nonadjustable, threshold sensitivity for the EnDat error message "Temperature exceeded" of the internal temperature sensor which, when triggered, transmits an EnDat error message (EnDat memory area "Operating condition," word 0 – "Error messages," bit 2² – "Position," and in the additional datum 2 "Operating condition error sources", bit 2⁶ – "Temperature exceeded"). This threshold sensitivity depends on the encoder and is shown in the specifications.

HEIDENHAIN recommends adjusting the threshold sensitivity so that it lies below the threshold sensitivity for the EnDat error message "Temperature exceeded" by a sufficient value. Compliance with the permissible operating temperature with respect to the measuring point M1 is definitive for the intended use of the encoder.

Electrical connection – cable

Cables inside the motor housing with wires for temperature sensor		
Complete with PCB connector (12-pin and 4-pin) and M23 right-angle socket (male), 9-pin		ID 746254-01 EPG Ø 4.5 mm; [6×2×0.09 mm ²]
Complete with PCB connector (12-pin and 4-pin) and M12 flange socket (male), 8-pin		ID 746820-01 ¹⁾ TPE 0.14 mm single leads ² with braided sleeving

1) **Note for safety-related applications:** Provide bit error rate as per specification 533095!

PUR connecting cable Ø 6 mm; [(4×0.14 mm ²) + (4×0.34 mm ²); A _P = 0.34 mm ²	M12 connector, 8-pin	M23 connector, 9-pin	
Complete with connector (female) and M12 coupling (male), 8 pins each		ID 368330-xx	ID 745796-xx
Complete with M12 connector (female), 8-pin and D-sub connector (female), 15-pin		ID 533627-xx	-
Complete with M12 connector (female), 8-pin and D-sub connector (male), 15-pin		ID 524599-xx	-
With one M12 connector (female), 8-pin		ID 634265-xx ¹⁾	-


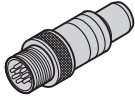
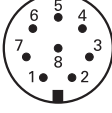

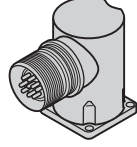
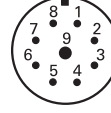
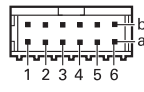








A_P: Cross section of power supply lines

1) Connecting element must be suitable for the maximum clock frequency used.

Note for safety-related applications: Provide bit error rate as per specification 533095!

Electrical connection

Pin layout

8-pin coupling or flange socket M12   		9-pin M23 right-angle socket   								
12-pin PCB connector  		4-pin PCB connector  								
	Power supply voltage			Absolute position values				Other signals ¹⁾		
 M12	8	2	5	1	3	4	7	6	/	/
 M23	3	7	4	8	5	6	1	2	/	/
 12	1b	6a	4b	3a	6b	1a	2b	5a	/	/
 4	/	/	/	/	/	/	/	/	1a	1b
	U_P	Sensor U_P	0 V	Sensor 0 V	DATA	DATA	CLOCK	CLOCK	T⁺ ²⁾	T⁻ ²⁾
	Brown/ Green	Blue	White/ Green	White	Gray	Pink	Violet	Yellow	Brown	³⁾

1) Only with adapter cables inside the motor

2) Connections for external temperature sensor; evaluation optimized for KTY 84-130 (see *Temperature measurement in motors* in the *Encoders for Servo Drives* catalog); connection in the M23 flange socket

3) **White** with M23 flange socket; **green** with M12 flange socket

Cable shield connected to housing; **U_P** = Power supply

Sensor: The sensor line is connected in the encoder with the corresponding power line

Vacant pins or wires must not be used!

Note for safety-oriented applications: Only HEIDENHAIN cables complete with connectors are qualified for use. Exchange connectors or modify cables only after consultation with HEIDENHAIN Traunreut.

HEIDENHAIN

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This Product Information supersedes all previous editions, which thereby become invalid. The basis for ordering from HEIDENHAIN is always the Product Information valid when the contract is made.

Related documents: Adhere to the information in the following documents to ensure the correct and intended operation of the encoder:

- Catalog: *Position Encoders for Servo Drives*: 208922-xx
- Mounting Instructions for *ECN 1325, EQN 1337*: 686161-xx
- Technical Information: *Safety-Related Position Measuring Systems*: 596632
- For implementation in a safe control or inverter: *Specification*: 533095