

HEIDENHAIN



Product Overview

Rotary Encoders for the Elevator Industry

Rotary encoders for the elevator industry

The demands on elevator technology have been growing steadily over these last several years: They call for high speeds and large heights together with compact design and low operating costs. And all that, of course, with optimal passenger comfort. Smooth starting and continuous acceleration are as much a prerequisite for a comfortable ride without unpleasant loads as are gentle braking and exact stopping at the target position.

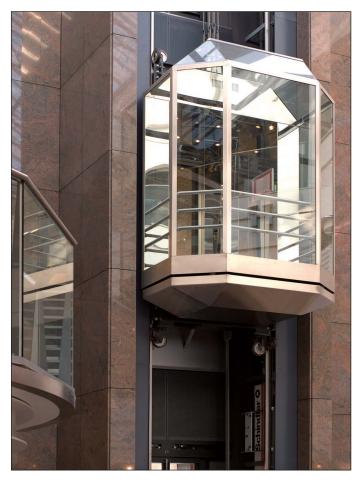
The **drive control plays** an important role here. The trend continues toward gearless drive machines, which offer a series of economical and environmental advantages:

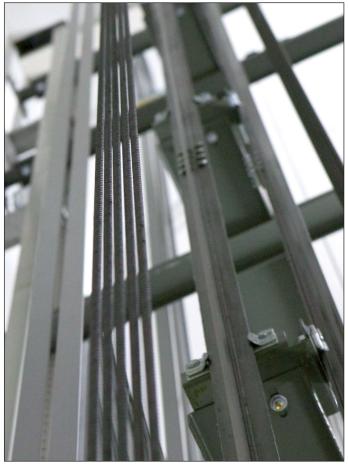
- Elevator systems with little vibration or noise
- Reduced space requirement thanks to machine-room-less elevators (MRL)
- Comfortable ride properties
- Low energy consumption
- Freedom from maintenance and oil

Permanent-magnet synchronous motors are often used because of their greater power density. Depending on the control strategy, these types of motors require absolute position information for correctly controlling the rotor position. This position information can be provided by an absolute rotary encoder or an incremental rotary encoder with commutation signals, for example.

In addition, these demanding drive strategies mostly require high-resolution rotary encoders, which are integrated as position encoders in the control loop in order to ascertain the actual shaft speed. Absolute rotary encoders with the purely serial EnDat 2.2 interface are perfectly suited for this purpose. They offer not only a high resolution, but also features such as diagnostic capabilities, datum setting for motor commutation, and an extended voltage range for increased ampacity.

In order to fulfill the great expectations place on functionality and reliability, as well as to make a suitable and well thought-out system integration possible, rotary encoders used in elevator technology must fulfill very specific requirements. This applies to the other fields of application for rotary encoders in elevator technology as well: digital shaft resolution and the controlling of door drives.





Overview

Rotary encoders for drive control in elevators

In its product program, HEIDENHAIN offers solutions tailored to the drive technology in elevators, providing the greatest possible uniformity of mechanical mounting combined with very different electrical interfaces. Technical details such as stiff shaft connections, rotary encoder couplings with a high mechanical natural frequency or with extended running tolerances, simple mounting and powerful bidirectional interfaces (EnDat) for absolute rotary encoders are all standard for HEIDENHAIN. This can cover the entire spectrum of the usual drive amplifiers on the market as well as customary types of motors.

Rotary encoders from HEIDENHAIN are characterized by excellent signal quality and high accuracy, and as such are a guarantee for high-quality velocity control and exact positioning.

Encoders with EnDat interface (purely digital or with analog signals) offer the option of retrieving encoder parameters and predefined characteristic values of the motor and brake from an internal EEPROM. This can shorten commissioning time and prevent input error when entering parameters of the drive system. In addition, EnDat encoders offer the possibility of electronic position adjustment (zeroing).

Thus, the absolute position value of the measuring device can be adjusted to the orientation of the motor rotating field, eliminating complicated mechanical alignment. Depending on the encoder, diagnostic functions such as temperature evaluation and valuation numbers are available for assessing the encoder's functional reserves. When critical values change, preventive measures can be taken to avoid an unscheduled maintenance stop of the elevator.



ECN/ERN 1300 series (plug-in PCB) and ECN/ERN 400 (cable connection) with expanding ring coupling (with high natural frequency of the stator coupling)



ECN/ERN 1300 series (plug-in PCB) and ECN/ERN 400 (cable connection) with planesurface coupling (expanded running and mounting tolerances)



ECN/ERN 100 series Hollow shafts with inside diameters up to 50 mm

ERN incremental rotary encoders ECN absolute singleturn encoders

Model	Outside diameter ²⁾	Shaft version	Protection	Incremental signals	Signal periods per revolution	Absolute position values	Signal periods/ rev for commut.
ERN 120 ERN 130 ERN 180	87 mm	Hollow through shaft Ø 20 mm, 25 mm, 30 mm, 38 mm or 50 mm	IP64	TITL HTL V 1 VPP	1000 to 5000	_	_
ECN 113				√ 1 V _{PP}	2048	EnDat01	8192 (13 bits)
ECN 125				_	_	EnDat22	33554435 (25 bits)
ERN 1321 ¹⁾	58 mm	Taper shaft Ø 9.25 mm	ECN/ERN 400: IP64 ECN/ERN 1300: IP40		1024 to 10000	_	_
ERN 1326 ¹⁾		Taper 1:10			1024, 2048, 4096 or 8192	UVW	3 signals for block commutation
ERN 1381 ¹⁾				∼ 1 V _{PP}	512, 1024, 2048, 4096	-	
ERN 1387 ERN 487				∼ 1 V _{PP}	2048	∼1V _{PP}	Z1 track for sine commutation
ECN 1313 ECN 413					2048	EnDat01	8192 (13 bits)
ECN 1325 ECN 425				_	_	EnDat22	33554435 (25 bits)

¹⁾ Only in version with expanding ring coupling; 2) Rotary encoder housing

Rotary encoders for digital shaft resolution

The shaft resolution serves to brake the elevator cabin without jerk in a timely manner, as well as to position it exactly. The position of the cabin is captured at all times and transmitted to the control. Incremental rotary encoders, and especially absolute rotary encoders from HEIDENHAIN are well suited to this purpose. They make digital shaft resolution possible, with its distinct advantages regarding control technology and mounting efforts

The special advantage of position detection with absolute multiturn rotary encoders is the availability at any time of the cabin's absolute position (even after power failure).

And since the actual position value is permanently on hand, the cabin can be moved directly to the entrance.

An RIQ 400 or a bearing assembly with an EQN 400 is offered specifically for shaft resolution. The cabin position is often measured through toothed belts and deflection pulleys. A bearing assembly decouples the large forces that often occur here from the precision bearing of the rotary encoder, thereby preventing an overload on the encoder.



Bearing assembly with EQN 400 Shaft load up to Axial 150 N Radial 350 N



RIQ 400 series (clamping flange) Shaft load up to Axial 100 N Radial 125 N



EQN 400 series

EQN/IQN absolute multiturn rotary encoders with mounted stator coupling RIQ absolute multiturn rotary encoders for separate shaft coupling

	Model	Outside dia. ¹⁾	Shaft version	Protection	Incremental signals	Signal periods per revolution	Absolute position values	Position values per revolution	Revo- lutions
	EQN 425	58 mm	shaft or hollow through shaft, Ø 12 mm	IP 64	~ 1 V _{PP}	512 or 2048	EnDat01	8192 (13 bits)	4096
						512	SSI		
Ī	IQN 425			IP66		32	EnDat01		
							SSI		
	RIQ 425	58 mm	Solid shaft Ø 10 mm (clamping flange) or Ø 6 mm (synchro flange)	IP66	∼1 V _{PP}	32	EnDat01	8192 (13 bits)	4096

¹⁾ Rotary encoder housing

Overview

Rotary encoders for door drives

Shorter holding times and thus an increase in the transport of passengers is the main goal especially for large transport capacities in office buildings with a high volume of public traffic. Correct operation of the elevator doors is a particularly critical topic in managing the pedestrian traffic of a large office building.

Fast and precise opening and closing with minimal noise development require controlled door drives. Compact rotary encoders from HEIDENHAIN are especially suited for speed and position feedback. Their mounting diameter of less than 40 mm makes them ideal for when space is limited.



ERN 1123







ERO 1420 ECI/EBI 1100 series

ERN 1023

ERO modular incremental rotary encoders ERN incremental rotary encoders ECI absolute singletum rotary encoders EBI absolute multitum rotary encoders

LDI absolu	· ·	lotary encouers						
Model	Outside dia. ¹⁾	Shaft version	Protection	Incremental signals	Signal periods per revolution	Absolute position values	Position values per revolution	Revo- lutions ²⁾
ERO 1420	38.4 mm	Hollow through shaft Ø 4 mm, 6 mm or 8 mm	IP00	ГШП	512, 1000 or 1024	-	_	-
ERN 1020 ERN 1030 ERN 1080		Blind hollow shaft Ø 6 mm	IP 64	□□ TTL □□ HTL ∼ 1 V _{PP}	100 to 3600	-	_	_
ERN 1023			IP 64		500 to 2048	UVW	3 signals for block commutation	_
ECI 1118	37 mm		IP00	_	_	EnDat22	262 144 (18 bits)	_
EBI 1135								65 536

¹⁾ Rotary encoder housing

With battery-buffered revolution counter

For more information

For more detailed information such as general technical descriptions, mounting instructions, technical specifications and exact dimensions, please refer to our brochures and product information documents, or visit us on the Internet at www.heidenhain.de



Product Information

ECN 413 ECN 425 ERN 487

Contents:

Rotary encoders for elevator drive control (IP64 degree of protection)



Product Information

ECN 1313

ECN 1325 ERN 1387

Contents:

Rotary encoders for servo drive control in elevators



Brochure

Encoders for Servo Drives

Contents: Rotary encoders Angle encoders Linear encoders



Brochure

Rotary Encoders

Contents:

Incremental rotary encoders

ERN, ROD

Absolute rotary encoders

ECN, EQN, ROC, ROQ

Comprehensive descriptions of all available interfaces as well as general electrical information are included in the *Interfaces* brochure.



Brochure
Interfaces of
HEIDENHAIN Encoders

HEIDENHAIN

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